

Automation for a Changing World

Delta AC Servo System ASDA-B2 Series







High Precision. High Response. Cost Effective.

Delta Electronics' new high-performance, cost-effective ASDA-B2 series servo motors and drives meet the requirements for general-purpose machine tools and enhance the competitive advantage of servo systems.

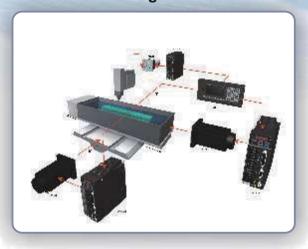
The power rating of the ASDA-B2 series ranges from 0.1kW to 3kW. The superior features of this series emphasize built-in generic functions for general purpose applications and avoiding variable costs from mechatronics integration. Delta's ASDA-B2 makes it convenient to complete assembly, wiring and operation setups. Switching from other brands is quick and easy due to the ASDA-B2's outstanding quality and features, and complete product lineup. The ASDA-B2 satisfies the requirements of general-purpose machine tools.

Customized solutions for different industries are available on request which is why the ASDA-B2 is popularand always in demand by customers in the field of industrial automation.

Transportation Machine



Electro-discharge Machine



Cutting Machine







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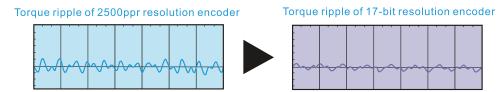
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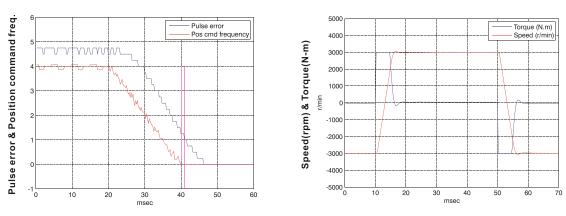
Features

Implements High Precision Positioning Control

- High-resolution encoder with 17-bit (160,000 p/rev) is a standard feature which satisfies the application needs of high precision positioning control and stable rotation at low speed.
- New 17-bit resolution encoder can reduce cogging torque to enhance the precision of the motor.



- Outstanding response characteristic: Up to 550kHz frequency response and settling time is below 1ms.
- 10ms acceleration time from -3000r/min to 3000r/min when running without load.



This example is frame size 60mm, 400W servo motor

Satisfies a Variety of Demands in the Industry

- Built-in position, speed and torque three control modes (speed and torque mode can be controlled via internal parameters or analog voltage command).
- High-speed line receiver command (4Mpps) is acceptable for high precision positioning control.

Two auto notch filters are provided to suppress the mechanical resonance automatically and make the system operate more smoothly.

 Lead friction compensation parameter is specified for the application of circular interpolation,
 Z-axis motion and ball screw, etc. so as to reduce the loading of the controller.

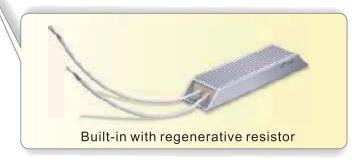
For bar feeders and other equipment requiring high torque output, motor protection parameters are offered to ensure that the mechanical system is not easily damaged.



Offers Easy-To-Install Solution For Simple Start-Up

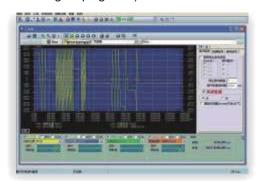


- Existing power cables and encoder cables can still be used for the ASDA series When upgrading, there is no need to purchase new accessories.
- Servo motor provides brake, oil seal, etc. optional configurations for the requirements of different applications.
- The control circuit and main power circuit is separated, safety is increased and maintenance is much easier.
- 400W and above servo drive is built-in with regenerative resistor, for significant savings on wiring and cost.



Fulfills Easy-To-Use Requirements For Versatile Operation

- Motor sizing software is offered for convenient estimation of equipment.
 Charge LED
- ASDA-Soft configuration software (tuning software)
 is provided to meet performance requirements quickly.
- Easy-to-use digital keypad is ideal for setting parameters and monitoring the servo drive and motor directly.
- Specific software communication cable ASD-CNUS0A08(Optional) for direct connection to PC increases communication quality and convenience of operation. (please refer to optional accessories on catalogue page 24)



 4 channels on-line monitoring function (similar to a digital oscilloscope) is available.
 The monitoring data could be 16-bit (4 channels) and 32-bit (2 channels) data.



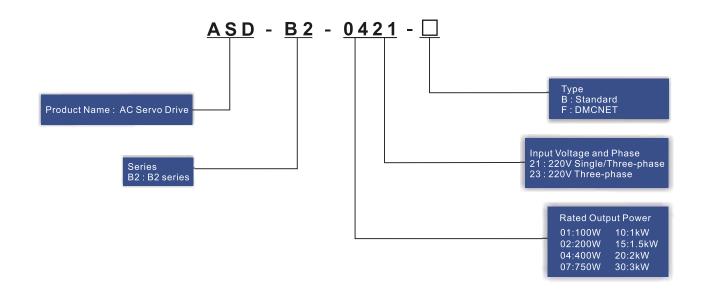
■ Multi-functional parameter editor function helps the users to edit, modify, upload / download and print desired parameters in real-time.



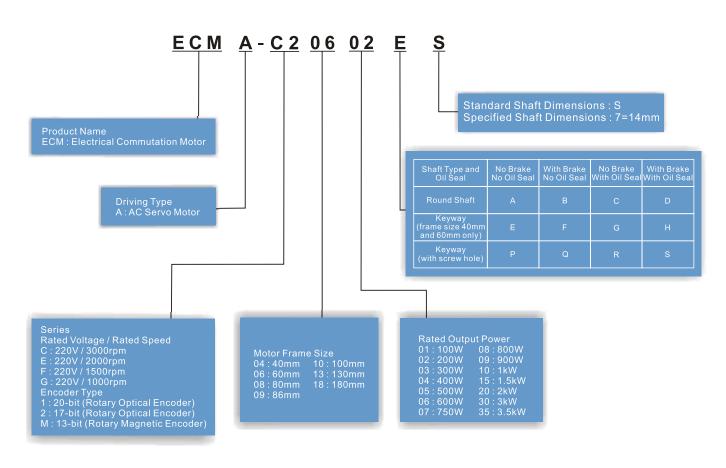
LED Display

Model Explanation

ASDA-B2 Series Servo Drives



ECMA Series Servo Motors



Product Line-up



Servo Motor								
Ser	ECMA-C∆0401∏S	ECMA-C∆0602∏S	ECMA-C\(\triangle 0604 \rightarrow S\) ECMA-CM0604PS ECMA-C\(\triangle 0804 \rightarrow 7\) ECMA-E\(\triangle 1305 \rightarrow S\) ECMA-G\(\triangle 1303 \rightarrow S\)	ECMA-C∆0807∏S ECMA-G∆1306∏S ECMA-GM1306PS ECMA-C∆0907∏S	ECMA-C\(\triangle 1010 \) S ECMA-E\(\triangle 1310 \) S ECMA-G\(\triangle 1309 \) S ECMA-GM1309PS ECMA-C\(\triangle 0910 \) S ECMA-F\(\triangle 1308 \) S	ECMA-E∆1315∏S	ECMA-C∆1020∏S ECMA-E∆1320∏S ECMA-E∆1820∏S	ECMA-E∆1830□S ECMA-F∆1830□S ECMA-E∆1835□S ECMA-C∆1330□4

Note:

- 1. (\square) in the model names are for optional configurations (keyway, brake and oil seal).
- 2. \triangle in the model names are for encoder resolution types \triangle 1: Incremental encoder, 20-bit; \triangle 2: Incremental encoder, 17-bit).



Part Names and Functions

LED Display

■ The 5 digit, 7 segment LED displays the servo status or fault codes.

Charge LED

■ A lit LED indicates that either power is connected to the servo drive or a residual charge is present in the drive's internal power components.

Operation Panel

■ Function keys used to perform status display, monitor and diagnostic, function and parameter setting. Function Keys:

MODE: Press this key to select/change mode SHIFT: Press this key to shift cursor to the left

▲ : Press this key to increase values on the display

▼ : Press this key to decrease values on the display

SET: Press this key to store data

Control Circuit Terminal (L1c, L2c)

■ Used to connect 100~230Vac, 50/60Hz single-phase or three-phase VAC supply.

Main Circuit Terminal (R, S, T)

■ Used to connect 200~230Vac, 50/60Hz commercial power supply.

Servo Motor Output (U, V, W)

■ Used to connect servo motor. Never connect the output terminal to main circuit power as the AC drive may be damaged beyond repair if incorrect cables are connected to the output terminals.

Internal & External Regenerative Resistor Terminal

- 1.When using an external resistor, connect it to P \oplus and C, and ensure an open circuit between P \oplus and D.
 - 2. When using an internal resistor, ensure the circuit is closed between P⊕ and D, and the circuit is open between P⊕ and C.
 - 3. When using external braking unit, connect braking unit to $P\oplus$ and \ominus , and ensure an open circuit between $P\oplus$ and D, and $P\oplus$ and C.

Ground Terminal

■ Used to connect grounding wire of power supply and servo motor.







Used to connect Delta's DVP series PLC or other external controllers for controlling I/O signals.

Motor Encoder Interface

■ Used to connect the encoder of the servo motor

Serial Communication Port

■ Used to connect PLC, HMI, etc. controllers for RS-485 / RS-232 serial communication.

Analog Voltage Output Terminal

■ Used to provide two analog monitor outputs, MON1 and MON2.

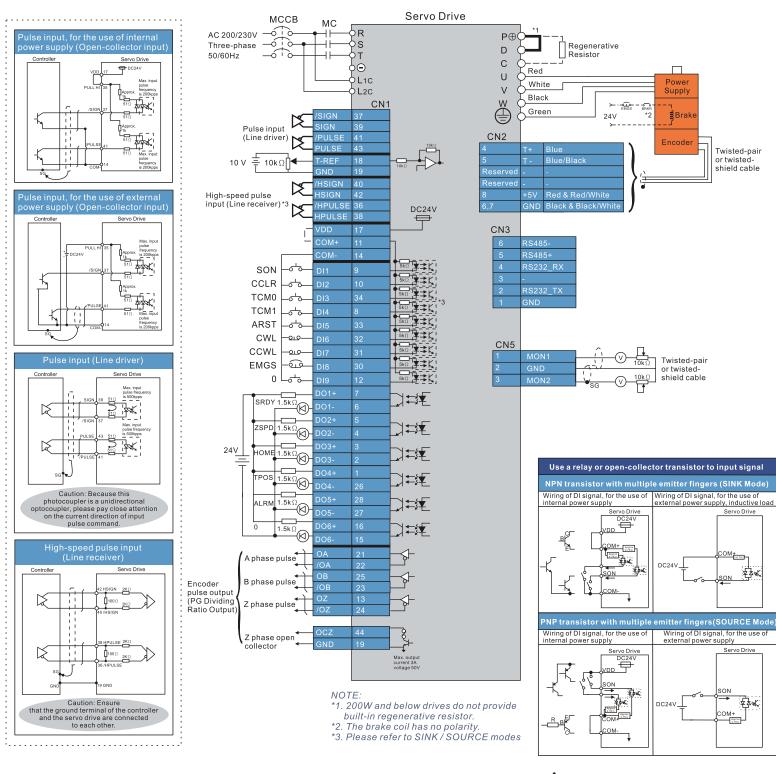
Heatsink

■ Used to secure servo drive and for heat dissipation.



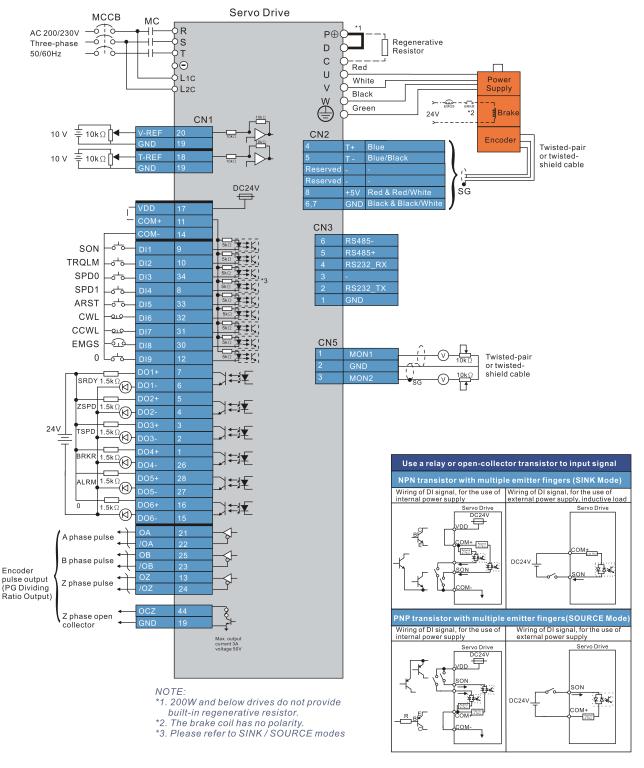
Standard Connection Examples

Position (Pt) Control Mode (for Pulse Command Input)



observe this caution may result in damage to the WARNING servo drive and servo motor.

Speed (S) Control Mode



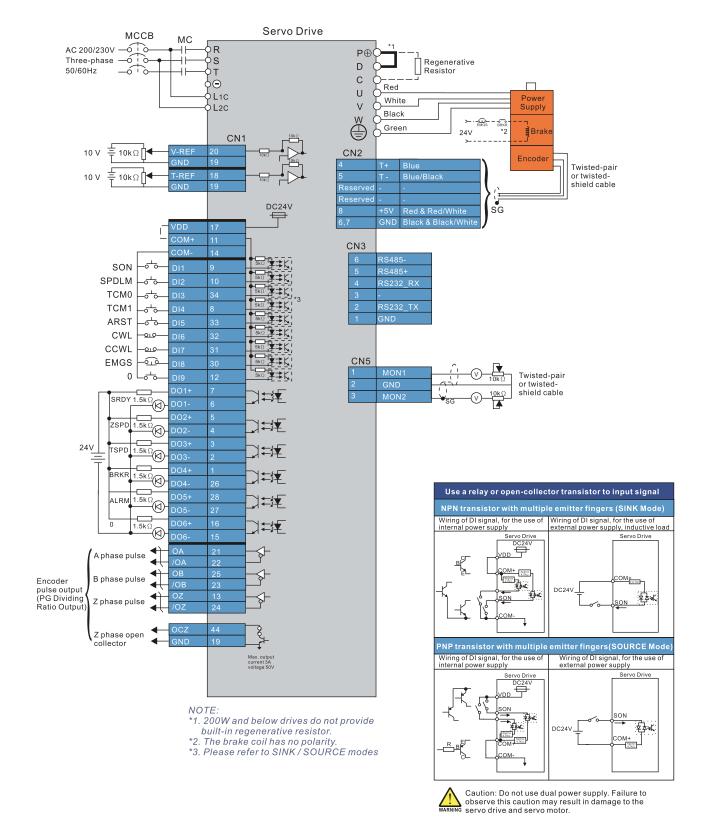


Caution: Do not use dual power supply. Failure to observe this caution may result in damage to the servo drive and servo motor.



Standard Connection Examples

Torque (T) Control Mode



Regenerative Resistor

Servo Drive	Recommended S Built-in Regener	Specifications for ative Resistor	Recommended Specifications for	Min. Allowable
(kW)	Resistance (Ohm) (parameter P1-52)	Capacity (Watt) (parameter P1-53)	External Regenerative Resistor	Resistance (Ohm)
0.1			80Ω	60Ω
0.2			80Ω	60Ω
0.4	100Ω	60W	200	60Ω
0.75	100Ω	60W	200	60Ω
1.0	40Ω	60W	40Ω	30Ω
1.5	40Ω	60W	40Ω	30Ω
2.0	20Ω	100W	30Ω	15Ω
3.0	20Ω	100W	30Ω	15Ω

Note

- ♦ There is no built-in regenerative resistor for 200W and below ASDA-B2 series servo drives.
- ♦ When the fault, ALE05 (Regeneration Error) occurs, please increase the regenerative resistor capacity or decrease the regenerative resistor resistance (the regenerative resistor resistance should not be less than the minimum allowable resistance listed in the above table.)
- ♦ If the situation is not improved after increasing the regenerative resistor capacity or decreasing the regenerative resistor resistance, please purchase regenerative resistor module.
- ♦ When combining multiple small-capacity regenerative resistors in parallel to increase the regenerative resistor capacity, make sure that the total resistance value of the regenerative resistors should not be less than the minimum allowable resistance listed in the above table.

Safety Information

Global Standards	ASDA-B2 series is designed to fully comply with demanding international standards, i.e. IEC and EN, etc. for all fields of industrial automation technology.					
	EN61000-4-6 Level 3					
	EN61000-4-3 Level 3					
5MO ()	EN61000-4-2 Level 2 and 3					
EMS standard	EN61000-4-4 Level 3					
	EN61000-4-8 Level 4					
	EN61000-4-5 Level 3					
Conducted & Radiated Emissions	Complies with EN550011 Class A Group 1, with external EMC filter					
CE Marking	CE recognized. Complies with Directive 2006/95/EC of the European Parliament and EMC Directive 2004/108/EC.					
Desta Con Dessay	IEC/EN50178, IEC/EN60529					
Protection Degree	IP20					
Vibration	1G less than 20Hz, 0.6G 20 to 50Hz. Complies with IEC/EN50178					
Shock	15gn 11ms. Complies with IEC/EN600028-2-27					
Pollution Degree	Degree 2. Complies with IEC/EN61800-5-1					
Ambient Temperature	Operating: 0C~55C (If operating temperature exceeds the specifications, forced cooling will be required.) Storage: -20C~65C					
Cooling Type	ASD-B2-0121-B, ASD-B2-0221-B, ASD-B2-0421-B, ASD-B2-0721-B Natural Air Circulation					
Cooling Type	ASD-B2-1021-B, ASD-B2-1521-B, ASD-B2-2023-B, ASD-B2-3023-B Fan Cooling					
Altitude	Altitude 1000m or lower above sea level					

IEC: International Electrotechnical Commission

EN: Europaischen Normen

EMC: Electromagnetic Compatibility IP: Ingress Protection Ratings



Specifications

ASDA-B2 Series		100W	200W	400W	750W	1kW	1.5kW	2kW	3kW			
	ASDA-BZ	Series	01	02	04	07	10	15	20	30		
ply	Dhasa /	/	Thr	ee-phase	: 170 ~	255VAC	50/60Hz	2 5%		-phase 55VAC		
Sup	Pnase /	Voltage	Sin	gle-phase	: 200 ~	255VAC	50/60Hz	2 5%		0Hz 5%		
Power Supply			7.3 Arms	8.3 Arms	13.4 Arms	19.4 Arms						
	Cooling S	System	N	atural Air	Circulati	on		Fan C	ooling			
	Encoder Re Feedback F		17-bit (160,000 p/rev)									
	Control of M	ain Circuit	SVPWM Control									
	Tuning N	Modes				Auto /	Manual					
	Dynamic	Brake	No	one			Built	t-in				
	Max. Input Ρι	ulse Frequency	Max. 50					Max. 4Mpp Open colle		eceiver)		
lode	Puls	е Туре	Puls	se + Direc	ction; A	phase + E	B phase;	CCW pul	se + CW	pulse		
<u>≥</u> o.	Comma	nd Source		Е	xternal p	ulse train	/ Internal	paramet	ers			
ontr	Smoothir	ng Strategy			Lov	v-pass an	d Moving	filter				
Position Control Mode	Electronic Gear			Electronic gear N/M multiple N: 1 ~(2 ²⁶ -1), M: 1 ~(2 ³¹ -1) (1/50 <n m<25600)<="" td=""></n>								
Po	Torque Limit Operation					Set by pa	rameters	3				
	Feed Forward	Compensation			;	Speed Co	ntrol Mod	le				
		Voltage Range $0 \sim \pm 10 \text{ V}_{DC}$										
	Analog Input Command	Input Resistance	sistance 10K									
		Time Constant	2.2 us									
ontrol Mode	Speed Co	ontrol Range ^{*1}	1:5000									
M Io	Comma	and Source		Ext	ernal ana	ilog signa	l / Interna	ıl parame	ters			
ontr	Smoothi	ing Strategy			Low	-pass and	S-curve	filter				
O p		mit Operation			Set by pa	rameters	or via An	alog input				
Speed		cy Response acteristic				Maximu	m 550Hz					
			0	.01% or le	ess at loa	d fluctuat	ion 0 to 10	00% (at ra	ited spee	d)		
	Speed Fluc	tuation Rate ^{⁺₂}		0.01% or	less at po	wer fluct	uation ±10	0% (at rat	ed speed)		
				0.01%	or less a 0 °C	at ambien to 50 °C (a	t tempera at rated s	ture flucti peed)	uation			
ge		Voltage Range				0 ~ ±	10 V _{DC}					
Mo	Analog Input Command	Input Resistance				10	K					
ntro		Time Constant				2.2	us					
Torque Control Mode	Comma	and Source		Ext	ernal ana	alog signa	II / Interna	al parame	ters			
rque	Smoothi	ing Strategy					iss filter					
2	Speed Lir	mit Operation	Parameter Setting or via Analog input									

	4004		100W	200W	400W	750W	1kW	1.5kW	2kW	3kW		
	ASDA-I	B2 Series	01	02	04	07	10	15	20	30		
	Analog Mo	onitor Output	Monitor signal can set by parameters (Output voltage range: ±8V)									
Di	Input Digital Input/ Output		Forv Spee	Spevard / Revolution of the second step se	ed/Torque verse inhi e mode sv lection in	e limit ena bit limit, F vitching, ⁻ out, Feed	abled, Em Position / : Forque / P step mod	ear, Zero s ergency s Speed mo osition m e input, A or) selecti	top, de switch ode switc uto run ir	ning, ching,		
			Er	ncoder sig	gnal outpu	ut (A, B, Z	Line Driv	er/ZOpe	n collect	or)		
Output			Servo ready, Servo On, At Zero speed, At Speed reached, At Positioning completed, At Torques limit, Servo alarm (Servo fault) activated, Electromagnetic brake control, Homing completed, Output overload warning Servo warning activated, Internal position command completed									
	Protectiv	e Functions	Overcurrent, Overvoltage, Undervoltage, Regeneration error, Overload, Overspeed, Abnormal pulse control command, Excessive deviation, Watch dog execution time out, Encoder error, Adjustment error, Emergency stop activated, Reverse/ Forward limit switch error, IGBT temperature error, Memory error, DSP communication error, Serial communication error, Input power phase loss, Serial communication time out, Command write-in error, terminals with short circuit protection (U, V, W, CN1, CN2, CN3 terminals)									
	Communica	ation Interface	RS-232 / RS-485									
	Insta	allation Site	Indoor location (free from direct sunlight), no corrosive liquid and gas (far away from oil mist, flammable gas, dust)									
	1	Altitude		A	Altitude 1	000m or l	ower abov	ve sea lev	el			
	Atmosp	heric Pressure				86kPa	~ 106kPa					
	Operatir	ng Temperature		0°C ~ 5		erating te cooling v		re is abov uired)	e 45°C,			
ıt	Storage	e Temperature				-20℃	~ 65℃					
mc	H	lumidity			0 to	90% (non	-condens	ing)				
Environment	V	ibration/	201	Hz以下 9.	80665m/s	s² (1G)	, 20 ~ 50	Hz 5.88m	/ s² (0.6	G)		
En	H	P Rating		IP20								
	Pow	ver System				TN Sy	′stem ^{*³}					
	A				61800-5-	1 CUL/cUL Safety Appro	US					

Footnote:

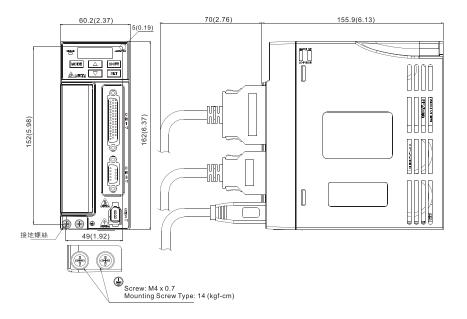
- *1 Rated rotation speed: When full load, speed ratio is defined as the minimum speed (the motor will not pause).
- *2 When command is rated rotation speed, the speed fluctuation rate is defined as: (Empty load rotation speed - Full load rotation speed) / Rated rotation speed
- *3 TN system: A power distribution system having one point directly earthed, the exposed conductive parts of the installation being connected to that point by a protective earth conductor.





Dimensions

100W / 200W / 400W



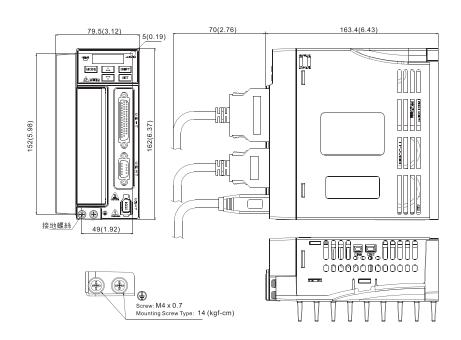
Weight 1.07 (2.36)



NOTE

1)Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)).
2)Dimensions and weights of the servo drives may be revised without prior notice.

750W

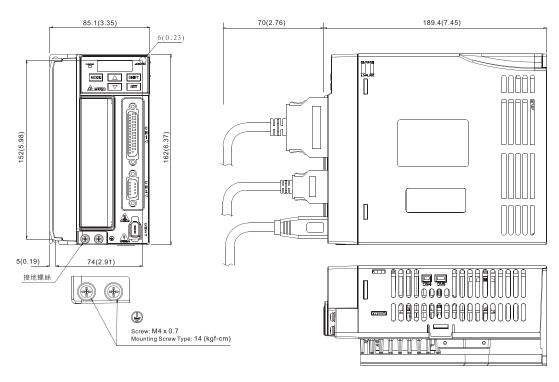


Weight 1.54 (3.40)



NOTE
1)Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)).
2)Dimensions and weights of the servo drives may be revised without prior notice.

1kW / 1.5kW



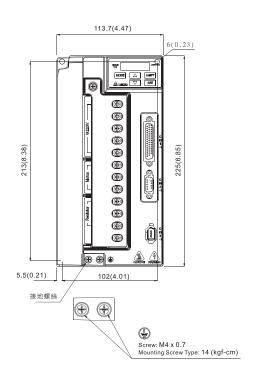
Weight 1.72 (3.79)

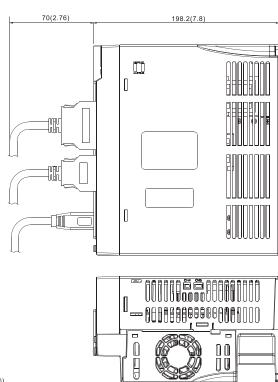


NOTE

1)Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)).
2)Dimensions and weights of the servo drives may be revised without prior notice.

2kW / 3kW





Weight



NOTE 1)Dimensions are in millimeters (inches); Weights are in kilograms (kg) and (pounds (lbs)).
2)Dimensions and weights of the servo drives may be revised without prior notice.



ECMA Specifications Low Inertia Series

Madala FOMA Carila a	C∆04	C/	706	C/	708	C/	709	C	:∆10	C∆13
Model: ECMA Series	01	02	04	04	07	07	10	10	20	30
Rated output power (kW)	0.1	0.2	0.4	0.4	0.75	0.75	1.0	1.0	2.0	3.0
Rated torque (N-m) ^{⁻¹}	0.32	0.64	1.27	1.27	2.39	2.39	3.18	3.18	6.37	9.55
Maximum torque (N-m)	0.96	1.92	3.82	3.82	7.16	7.14	8.78	9.54	19.1	28.65
Rated speed (r/min)			3000			30	00	3000		3000
Maximum speed (r/min)			5000			30	00	50	000	4500
Rated current (A)	0.90	1.55	2.60	2.60	5.10	3.66	4.25	7.30	12.05	17.2
Maximum current (A)	2.70	4.65	7.80	7.24	15.3	11	12.37	21.9	36.15	47.5
Power rating (kW/s)	27.7	22.4	57.6	22.1	48.4	29.6	38.6	38.1	90.6	71.8
Rotor moment of inertia (× 10⁻⁴kg.m²)(Without brake)	0.037	0.177	0.277	0.68	1.13	1.93	2.62	2.65	4.45	12.7
Mechanical time constant (ms)	0.75	0.80	0.53	0.73	0.62	1.72	1.20	0.74	0.61	1.11
Torque constant-KT (N-m/A)	0.36	0.41	0.49	0.49	0.47	0.65	0.75	0.44	0.53	0.557
Voltage constant-KE (mV/(r/min))	13.6	16.0	17.4	18.5	17.2	27.5	24.2	16.8	19.2	20.98
Armature resistance (Ohm)	9.30	2.79	1.55	0.93	0.42	1.34	0.897	0.20	0.13	0.0976
Armature inductance (mH)	24.0	12.07	6.71	7.39	3.53	7.55	5.7	1.81	1.50	1.21
Electrical time constant (ms)	2.58	4.30	4.30	7.96	8.36	5.66	6.35	9.30	11.4	12.4
Insulation class	Class A (UL), Class B (CE)									
Insulation resistance				>1001	MΩ , DC	500V				
Insulation strength				1500V	AC, 60 se	econds				
Weight (kg) (without brake)	0.5	1.2	1.6	2.1	3.0	2.9	3.8	4.3	6.2	6.2
Weight (kg) (with brake)	8.0	1.5	2.0	2.9	3.8	3.69	5.5	4.7	7.2	7.2
Max. radial shaft load (N)	78.4	196	196	245	245	245	245	490	490	490
Max. thrust shaft load (N)	39.2	68	68	98	98	98	98	98	98	98
Power rating (kW/s) (with brake)	25.6	21.3	53.8	22.1	48.4	29.3	37.9	30.4	82.0	82.0
Rotor moment of inertia (× 10⁴kg.m²) (with brake)	0.04	0.19	0.30	0.73	1.18	1.95	2.67	3.33	4.95	4.95
Mechanical time constant (ms) (with brake)	0.81	0.85	0.57	0.78	0.65	1.74	1.22	0.93	0.66	0.66
Brake holding torque [Nt-m (min)]	0.3	1.3	1.3	2.5	2.5	2.5	2.5	8.0	8.0	8.0
Brake power consumption (at 20C) [W]	7.2	6.5	6.5	8.2	8.2	8.2	8.2	19.4	19.4	19.4
Brake release time [ms (Max)]	5	10	10	10	10	10	10	10	10	10
Brake pull-in time [ms (Max)]	25	70	70	70	70	70	70	70	70	70
Vibration grade (μm)						15				
Operating temperature (C)					0 -	~ 40				
Storage temperature (C)					-10	~ 80				
Operating humidity	20 ~ 90%RH (non-condensing)									
Storage humidity	20 ~ 90%RH (non-condensing)									
Vibration capacity					2.	.5G				
IP Rating	IF				nectors a iting shat					d to
Approvals					E Mark	D _{US}				
Footnote: *1 Rate torque values are continuous permissible values at 0~4000	ambient temperat	ure when attaching	with the sizes of he	safety atsinks listed belov	r пруточев Satety A	pproved				

Footnote: *1 Rate torque values are continuous permissible values at 0~40oC ambient temperature when attaching with the sizes of heatsinks listed below: ECMA-__04 / 06 / 08 : 250mm x 250mm x 5mm
ECMA-__11: 300mm x 300mm x 12mm
ECMA-__13: 400mm x 300mm x 20mm
ECMA-__13: 400mm x 50mm x 50mm x 50mm
ECMA-__18: 550mm x 550mm x 550mm x 50mm x 50mm
ECMA-__18: 550mm x 550mm x 50mm x 50

Medium / High Inertia Series

		E∠	<u>\</u> 13			E∆18		F∆13	F∆18		G∆13	
Model: ECMA Series	05	10	15	20	20	30	35	08	30	03	06	09
Rated output power (kW)	0.5	1.0	1.5	2.0	2.0	3.0	3.5	0.85	3.0	0.3	0.6	0.9
Rated torque (N-m) 1	2.39	4.77	7.16	9.55	9.55	14.32	16.71	5.41	19.10	2.86	5.73	8.59
Maximum torque (N-m)	7.16	14.32	21.48	28.65	28.65	42.97	50.13	13.8	57.29	8.59	17.19	21.48
Rated speed (r/min)				200	00			1500 1000				
Maximum speed (r/min)				300	0			3000			2000	
Rated current (A)	2.9	5.6	8.3	11.01	11.22	16.1	19.2	16.1	19.4	2.5	4.8	7.5
Maximum current (A)	8.7	16.8	24.81	33.03	33.66	48.3	57.6	48.3	58.2	7.44	14.49	22.5
Power rating (kW/s)	7.0	27.1	45.9	62.5	26.3	37.3	50.8	37.3	66.4	10.0	39.0	66.0
Rotor moment of inertia $(imes 10^{-4} { m kg.m^2})$ (Without brake)	8.17	8.41	11.18	14.59	34.68	54.95	54.95	54.95	54.95	8.17	8.41	11.18
Mechanical time constant (ms)	1.91	1.51	1.11	0.96	1.62	1.06	1.08	1.06	1.28	1.84	1.40	1.07
Torque constant-KT (N-m/A)	0.83	0.85	0.87	0.87	0.85	0.89	0.87	0.89	0.98	1.15	1.19	1.15
Voltage constant-KE (mV/(r/min))	30.9	31.9	31.8	31.8	31.4	32.0	32	32.0	35.0	42.5	43.8	41.6
Armature resistance (Ohm)	0.57	0.47	0.26	0.174	0.119	0.052	0.052	0.052	0.077	1.06	0.82	0.43
Armature inductance (mH)	7.39	5.99	4.01	2.76	2.84	1.38	1.38	1.38	1.27	14.29	11.12	6.97
Electrical time constant (ms)	12.96	12.88	15.31	15.86	23.87	26.39	26.39	26.39	16.51	13.55	13.55	16.06
Insulation class	Class A (UL), Class B (CE)											
Insulation resistance					>1($00 M\Omega$,	DC 500	V				
Insulation strength					1500	V AC, 6	0 secor	ıds				
Weight (kg) (without brake)	6.8	7.0	7.5	7.8	13.5	18.5	18.5	18.5	18.5	6.8	7.0	7.5
Weight (kg) (with brake)	8.2	8.4	8.9	9.2	17.5	22.5	22.5	22.5	22.5	8.2	8.4	8.9
Max. radial shaft load (N)	490	490	490	490	1176	1470	490	1470	1470	490	490	490
Max. thrust shaft load (N)	98	98	98	98	490	490	98	490	490	98	98	98
Power rating (kW/s) (with brake)	6.4	24.9	43.1	59.7	24.1	35.9	48.9	35.9	63.9	9.2	35.9	62.1
Rotor moment of inertia (× 10⁴kg.m²) (with brake)	8.94	9.14	11.90	15.88	37.86	57.06	57.06	57.06	57.06	8.94	9.14	11.9
Mechanical time constant (ms) (with brake)	2.07	1.64	1.19	1.05	1.77	1.10	1.12	1.10	1.33	2.0	1.51	1.13
Brake holding torque [Nt-m (min)]	10.0	10.0	10.0	10.0	25.0	25.0	10.0	25.0	25.0	10.0	10.0	10.0
Brake power consumption (at 20C) [W]	21.0	21.0	21.0	21.0	20.4	20.4	19.0	20.4	20.4	19.0	19.0	19.0
Brake release time [ms (Max)]	10.0	10.0	10.0	10.0	5.0	10.0	10.0	10.0	10.0	10.0	10.0	10.0
Brake pull-in time [ms (Max)]	25.0	25.0	25.0	25.0	25.0	25.0	70	25.0	25.0	25.0	25.0	25.0
Vibration grade (μ m)						15	5					
Operating temperature (C)						0 ~	40					
Storage temperature (C)						-10 ~	80					
Operating humidity	20 ~ 90%RH(non-condensing)											
Storage humidity	20 ~ 90%RH(non-condensing)											
Vibration capacity	2.5G											
IP Rating		IP65 (an oil se el is use		ed to	
Approvals					(E (UL/cUL tty Approved					

:*1 Rate torque values are continuous permissible values at 0~40oC ambient temperature when attaching with the sizes of heatsinks listed below: ECMA.__ 04 / 06 / 08 : 250mm x 250mm x 260mm ECMA.__ 13 : 400mm x 400mm x 20mm ECMA.__ 13 : 400mm x 400mm x 20mm ECMA.__ 18 : 550mm x 550mm x 360mm x 30mm Material type: Aluminum F40, F60, F60, F100, F130, F180

Material type: Aluminum F40, F60, F60, F100, F130, F180

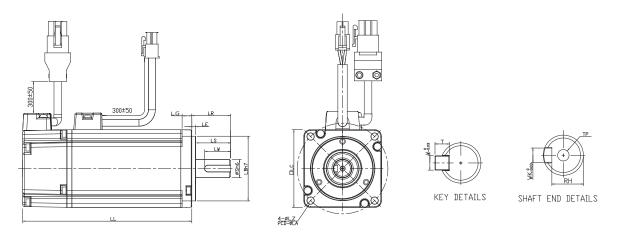
**3 For the specifications of the motors with rotary magnetic encoders, please refer to the specifications of the corresponding standard models.

**4 (\(\triangle \tria



Dimensions

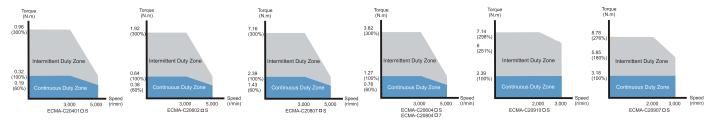
Motors - Frame Size 86mm and below (Units: mm)



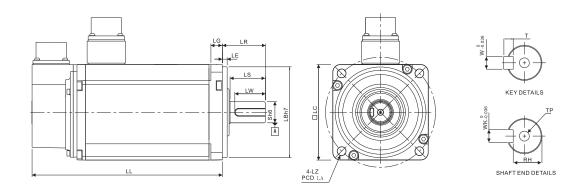
Model	C∆0401⊟S	C∆0602□S	C∆0604⊟S	C∆0804□S	C∆0807 <u></u> S	C∆0907∏S	C∆0910 <u>S</u>
LC	40	60	60	80	80	86	86
LZ	4.5	5.5	5.5	6.6	6.6	6.6	6.6
LA	46	70	70	90	90	100	100
S	8(+0.009)	14(+0 -0.011)	14(+0 -0.011)	14(+0 -0.011)	$19(^{+0}_{-0.013})$	16(+0 -0.011)	16(+0 -0.011)
LB	30(+0 -0.021)	50(+0 -0.025)	50(+0 -0.025)	70(+0 -0.030)	70(+0 -0.030)	80(+0-0.030)	80(+0-0.030)
LL(Without Brake)	100.6	105.5	130.7	112.3	138.3	130.2	153.2
LL(With Brake)	136.6	141.6	166.8	152.8	178	161.3	184.3
LS(Without Oil Seal)	20	27	27	27	32	30	30
LS(With Oil Seal)	20	27	27	27	32	30	30
LR	25	30	30	30	35	35	35
LE	2.5	3	3	3	3	3	3
LG	5	7.5	7.5	8	8	8	8
LW	16	20	20	20	25	20	20
RH	6.2	11	11	11	15.5	13	13
WK	3	5	5	5	6	5	5
W	3	5	5	5	6	5	5
Т	3	5	5	5	6	5	5
TP	M3 Depth 8	M4 Depth 15	M4 Depth 15	M4 Depth 15	M6 Depth 20	M5 Depth 15	M5 Depth 15



1. Dimensions are in millimeters. Weights are in kilograms (kg) and (pounds (lbs)).
2. Dimensions and weights of the servo motor may be revised without prior notice.
3. Except ECMA-CM0604PS LL:116,2mm, for the specifications of the motors with rotary magnetic encoders, please refer to the corresponding standard models.
4. (_) in the model names are for optional configurations (keyway, brake and oil seal).
5. (\(\triangle \) in the model names are for encoder resolution types (\(\triangle = 1 \): Incremental encoder, 20-bit; \(\triangle = 2 \): Incremental encoder, 17-bit).

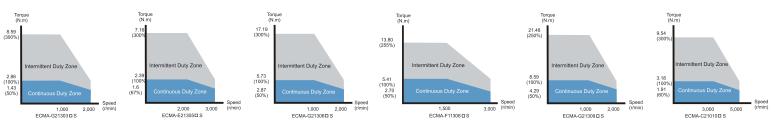


Motors - Frame Size 100mm ~ 130mm (Units: mm)



Model	G∆1303∏S	E∆1305∏S	G∆1306∏S	F∆1308□S	G∆1309 <u></u> S	C∆1010□S
LC	130	130	130	130	130	100
LZ	9	9	9	9	9	9
LA	145	145	145	145	145	115
S	22(+0 -0.013)	22(+0-0.013)	22(+0 -0.013)	22(+0 -0.013)	22(+0 -0.013)	22(+0 -0.013)
LB	110(+0 -0.035)	110(+0 -0.035)	110(+0/-0.035)	110(+0 -0.035)	110(+0 -0.035)	95(+0 _{-0.035})
LL(Without Brake)	147.5	147.5	147.5	152.5	163.5	153.3
LL(With Brake)	183.5	183.5	183.5	181	198	192.5
LS	47	47	47	47	47	37
LR	55	55	55	55	55	45
LE	6	6	6	6	6	5
LG	11.5	11.5	11.5	11.5	11.5	12
LW	36	36	36	36	36	32
RH	18	18	18	18	18	18
WK	8	8	8	8	8	8
W	8	8	8	8	8	8
Т	7	7	7	7	7	7
TP	M6 Depth 20	M6 Depth 20				

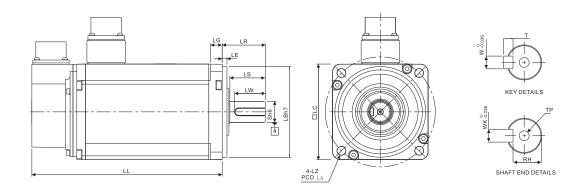
1. Dimensions are in millimeters. Weights are in kilograms (kg) and (pounds (lbs)).
2. Dimensions and weights of the servo motor may be revised without prior notice.
3. Except ECMA-CM0604PS LL:116,2mm, for the specifications of the motors with rotary magnetic encoders, please refer to the corresponding standard models.
4. () in the model names are for optional configurations (keyway, brake and oil seal).
5. () in the model names are for encoder resolution types (=1: Incremental encoder, 20-bit; =2: Incremental encoder, 17-bit).





Dimensions

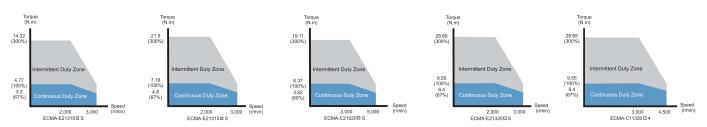
Motors - Frame Size 100mm ~ 130mm (Units: mm)



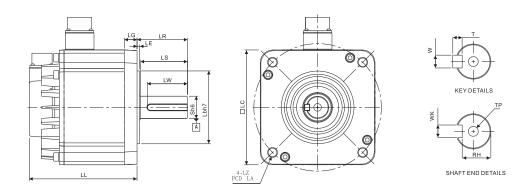
Model	E∆1310∐S	E∆1315∏S	C∆1020□S	E∆1320 <u></u> S	C∆1330? S4
LC	130	130	100	130	130
LZ	9	9	9	9	9
LA	145	145	115	145	145
S	22(+0 -0.013)	22(+0 -0.013)	22(+0 -0.013)	22(+0 -0.013)	24(+0 -0.013)
LB	110(+0 -0.035)	110(+0 -0.035)	95(+0.035)	110(+0.035)	110(+0/-0.035)
LL(Without Brake)	147.5	167.5	199	187.5	187.5
LL(With Brake)	183.5	202	226	216	216
LS	47	47	37	47	47
LR	55	55	45	55	55
LE	6	6	5	6	6
LG	11.5	11.5	12	11.5	11.5
LW	36	36	32	36	36
RH	18	18	18	18	20
WK	8	8	8	8	8
W	8	8	8	8	8
Т	7	7	7	7	7
TP	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20	M6 Depth 20



- 1. Dimensions are in millimeters. Weights are in kilograms (kg) and (pounds (lbs)).
 2. Dimensions and weights of the servo motor may be revised without prior notice.
 3. Except ECMA-CM0604PS LL:116,2mm, for the specifications of the motors with rotary magnetic encoders, please refer to the corresponding standard models.
 4. () in the model names are for optional configurations (keyway, brake and oil seal).
 5. () in the model names are for encoder resolution types (= 1: Incremental encoder, 20-bit; = 2: Incremental encoder, 17-bit).



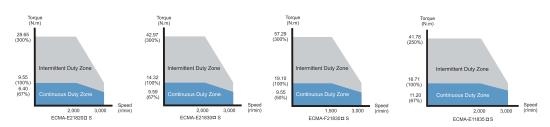
Motors - Frame Size 180mm and above (Units: mm)



Model	E∆1820 <u></u> S	E∆1830∏S	E∆1835∏S	F∆1830 <u></u> S
LC	180	180	180	180
LZ	13.5	13.5	13.5	13.5
LA	200	200	200	200
S	35(⁺⁰ _{-0.016})			
LB	114.3(+0 -0.035)	114.3(+0.035)	114.3(+0 -0.035)	114.3(+0 -0.035)
LL(Without Brake)	169	202.1	202.1	202.1
LL(With Brake)	203.1	235.3	235.3	235.3
LS	73	73	73	73
LR	79	79	79	79
LE	4	4	4	4
LG	20	20	20	20
LW	63	63	63	63
RH	30	30	30	30
WK	10 - 0.036	10_0.036	10_0.036	10_0.036
W	10_0.036	10_0.036	10 - 0.036	10 - 0.036
Т	8	8	8	8
TP	M12 Depth 25	M12 Depth 25	M12 Depth 25	M12 Depth 25



1. Dimensions are in millimeters. Weights are in kilograms (kg) and (pounds (lbs)).
2. Dimensions and weights of the servo motor may be revised without prior notice.
3. Except ECMA-CM0604PS LL:116,2mm, for the specifications of the motors with rotary magnetic encoders, please refer to the corresponding standard models.
4. () in the model names are for optional configurations (keyway, brake and oil seal).
5. () in the model names are for encoder resolution types (=1: Incremental encoder, 20-bit; =2: Incremental encoder, 17-bit).





Optional Accessories

Power Cables

- 3m and 5m standard cables are available.
- Customized service is offered to meet the needs of customers.
- Two types are selectable: with brake and without brake.





■ Used to connect to external (host) controller



CN1 Convenient Connector

■ Delta Part Number: ASD-IF-DS4444



Encoder Cables

- 3m and 5m standard cables are available.
- Customized service is offered to meet the needs of customers.





Regenerative Resistors

- 400W/40Ohm and 1kW/20Ohm two kinds of specifications are available.
- For selecting a regenerative resistor, please refer to the table of regenerative resistor specifications on page 12.



- 0.5M connection cable is provided.
 Easy to reduce the space required.
- Delta Part Number: ASD-MDDS4444



RS-485 Connectors

- Used to connect multiple Delta ASDA series products by RS-485 interface through Modbus serial communication.
- Delta Part Number: ASD-CNIE0B06



ASD-Soft Software Communication Cables (for PC)

■ Delta Part Number: ASD-CNUS0A08





Optional Accessories

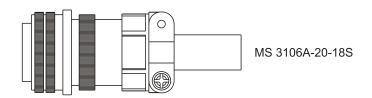
Power Connectors

ASDBCAPW0000



Title	Part No.	Manufacturer
Housing	C4201H00-2*2PA	JOWLE
Terminal	C4201TOP-2	JOWLE

ASD-CAPW1000

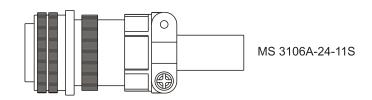


ASDBCAPW0100

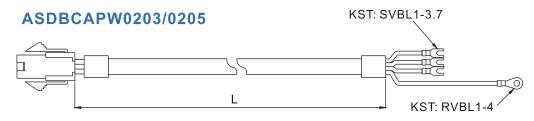


Title	Part No.	Manufacturer
Housing	C4201H00-2*3PA	JOWLE
Terminal	C4201TOP-2	JOWLE

ASD-CAPW2000

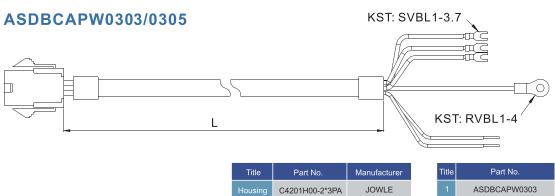


Power Cables



Title	Part No.	Manufacturer
Housing	C4201H00-2*2PA	JOWLE
Terminal	C4201TOP-2	JOWLE

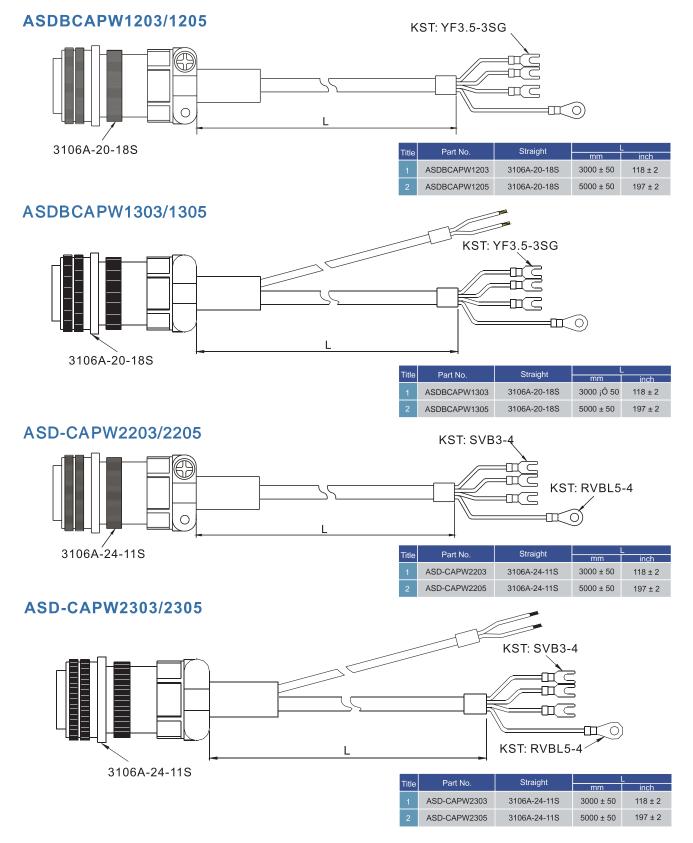
Title	Part No.		L	
Title	Fait No.	mm	inch	
1	ASDBCAPW0203	3000 ± 50	118 ± 2	
2	ASDBCAPW0205	5000 ± 50	197 ± 2	



JOWLE

C4201TOP-2





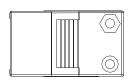


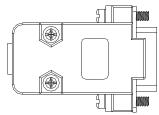
Optional Accessories

Encoder Connectors

ASDBCAEN0000



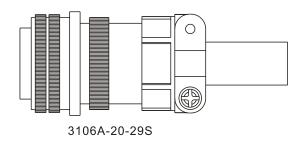


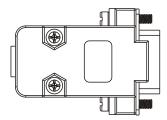


D-SUB Connector 9P

Title	Part No.	Manufacturer
Housing	AMP(1-172161-9)	AMP
Terminal	AMP(170359-3)	AMP
CLAMP	DELTA(34703237XX)	DELTA

ASDBCAEN1000

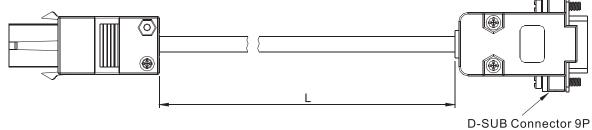




D-SUB Connector 9P

Encoder Cables

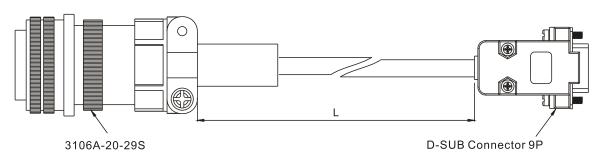




Title	Part No.		L
Title	Tait No.	mm	inch
1	ASDBCAEN0003	3000 50	118 2
2	ASDBCAEN0005	5000 50	197 2

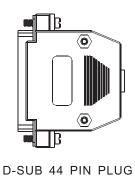
Title	Part No.	Manufacturer
Housing	AMP(1-172161-9)	AMP
Terminal	AMP(170359-3)	AMP
CLAMP	DELTA(34703237XX)	DELTA

ASDBCAEN1003/1005



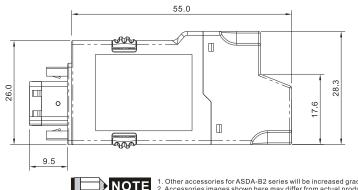
I/O Signal Connector

ASDBCNDS0044



RS-485 Connector

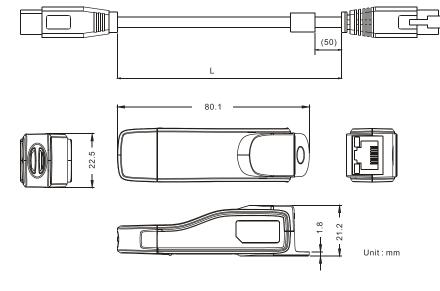
ASD-CNIE0B06



1. Other accessories for ASDA-B2 series will be increased gradually.
2. Accessories images shown here may differ from actual product.
Please refer to the actual product appearance.

Communication Cable between Drive and Computer (for PC)

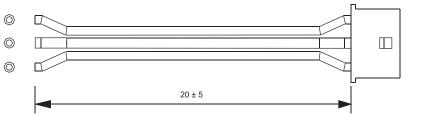
ASD-CNUS0A08



Title	Part No. : ASD-CNUS0A08		
O-bl-		3000 ± 100 mm	
Cable	L	118 ± 4 inch	
Connector	RJ connector	RJ-45	
	USB connector	A-type (USB V2.0)	

Voltage Output Cable (Analog Signal)

38644718XX



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Title	Part No.	Manufacturer
Housing	A2004H00-3P	JWT
Terminal	A2004TOP-2	JWT



Accessories Combinations

100 W Servo Drive and 100W Low Inertia Servo Motor

Servo Drive	ASD-B2-0121-□
Low Inertia Servo Motor	ECMA-C∆0401□S
Power Cables (Without Brake)	ASDBCAPW020X
Power Connectors (Without Brake)	ASDBCAPW0000
Power Cables (With Brake)	ASDBCAPW030X
Power Connectors (With Brake)	ASDBCAPW0100
Encoder Cables	ASDBCAEN000X
Encoder Connectors	ASDBCAEN0000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

200W Servo Drive and 200W Low Inertia Servo Motor

Servo Drive	ASD-B2-0221-□
Low Inertia Servo Motor	ECMA-C∆0602□S
Power Cables (Without Brake)	ASDBCAPW020X
Power Connectors (Without Brake)	ASDBCAPW0000
Power Cables (With Brake)	ASDBCAPW030X
Power Connectors (With Brake)	ASDBCAPW0100
Encoder Cables	ASDBCAEN000X
Encoder Connectors	ASDBCAEN0000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

400W Servo Drive and 400W Low Inertia Servo Motor

Servo Drive	ASD-B2-0421-□
Low Inertia Servo Motor	ECMA-C∆0604□S ECMA-C∆0804□7 ECMA-CM0604PS
Power Cables (Without Brake)	ASDBCAPW020X
Power Connectors (Without Brake)	ASDBCAPW0000
Power Cables (With Brake)	ASDBCAPW030X
Power Connectors (With Brake)	ASDBCAPW0100
Encoder Cables	ASDBCAEN000X
Encoder Connectors	ASDBCAEN0000

400W Servo Drive and 500W Medium Inertia Servo Motor

Servo Drive	ASD-B2-0421-□
Medium Inertia Servo Motor	ECMA-E∆1305⊟S
Power Cables (Without Brake)	ASDBCAPW120X
Power Connectors (Without Brake)	ASDBCAPW130X
Power Connectors	ASD-CAPW1000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

400W Servo Drive and 300W High Inertia Servo Motor

Servo Drive	ASD-B2-0421-□
High Inertia Servo Motor	ECMA-G∆1303□S
Power Cables (Without Brake)	ASDBCAPW120X
Power Connectors (Without Brake)	ASDBCAPW130X
Power Connectors	ASD-CAPW1000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

750W Servo Drive and 750W Low Inertia Servo Motor

Servo Drive	ASD-B2-0721-□
Low Inertia Servo Motor	ECMA-C∆0807□S ECMA-C∆0907□7
Power Cables (Without Brake)	ASDBCAPW020X
Power Connectors (Without Brake)	ASDBCAPW0000
Power Cables (With Brake)	ASDBCAPW030X
Power-Connectors (With Brake)	ASDBCAPW0100
Encoder Cables	ASDBCAEN000X
Encoder Connectors	ASDBCAEN0000



Accessories Combinations

750W Servo Drive and 600W High Inertia Servo Motor

Servo Drive	ASD-B2-0721-□
High Inertia Servo Motor	ECMA-G∆1306□S ECMA-GM1306PS
Power Cables (Without Brake)	ASDBCAPW120X
Power Cables (With Brake)	ASDBCAPW130X
Power Connectors	ASD-CAPW0100
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

1kW Servo Drive and 1kW Low Inertia Servo Motor

Servo Drive	ASD-B2-1021-□
Low Inertia Servo Motor	ECMA-C∆1010⊟S
Power Cables (Without Brake)	ASDBCAPW120X
Power Cables (With Brake)	ASDBCAPW130X
Power Connectors	ASD-CAPW1000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m) $\,$

1kW Servo Drive and 1kW Low Inertia Servo Motor

Servo Drive	ASD-B2-1021-□
Low Inertia Servo Motor	ECMA-C∆0910⊟S
Power Cables (Without Brake)	ASDBCAPW020X
Power Connectors (Wuthout Brake)	ASDBCAPW0000
Power Cables (With Brake)	ASDBCAPW030X
Power-Connectors (With Brake)	ASDBCAPW0100
Encoder Cables	ASDBCAEN000X
Encoder Connectors	ASDBCAEN0000

1kW Servo Drive and 1kW Medium Inertia Servo Motor

Servo Drive	ASD-B2-1021-□
Medium Inertia Servo Motor	ECMA-E∆1310□S
Power Cables (Without Brake)	ASDBCAPW120X
Power Cables (With Brake)	ASDBCAPW130X
Power Connectors	ASD-CAPW1000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

1kW Servo Drive and 850W Medium-High Inertia Servo Motor

Servo Drive	ASD-B2-1021-□
Medium-High Inertia Servo Motor	ECMA-F∆1308⊟S
Power Cables (Without Brake)	ASDBCAPW120X
Power Cables (With Brake)	ASDBCAPW130X
Power Connectors	ASD-CAPW1000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

1kW Servo Drive and 900W High Inertia Servo Motor

Servo Drive	ASD-B2-1021-□
High Inertia Servo Motor	ECMA-G∆1309□S ECMA-GM1309PS
Power Cables (Without Brake)	ASDBCAPW120X
Power -Cables (With Brake)	ASDBCAPW130X
Power Connectors	ASD-CAPW1000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

1.5kW Servo Drive and 1.5kW Medium Inertia Servo Motor

Servo Drive	ASD-B2-1521-⊡
Medium Inertia Servo Motor	ECMA-E∆1315⊡S
Power Cables (Without Brake)	ASDBCAPW120X
Power Cables (With Brake)	ASDBCAPW130X
Power Connectors	ASD-CAPW1000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000



Accessories Combinations

2kW Servo Drive and 2kW Low Inertia Servo Motor

Servo Drive	ASD-B2-2023-□
Low Inertia Servo Motor	ECMA-C∆1020⊟S
Power Cables (Without Brake)	ASDBCAPW120X
Power Cables (With Brake)	ASDBCAPW130X
Power Connectors	ASDBCAPW1000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

2kW Servo Drive and 2kW Medium Inertia Servo Motor

Servo Drive	ASD-B2-2023-□
Medium Inertia Servo Motor	ECMA-E∆1320⊡S
Power Cables (Without Brake)	ASDBCAPW120X
Power Cables (With Brake)	ASDBCAPW130X
Power Connectors	ASD-CAPW1000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m) $\,$

2kW Servo Drive and 2kW Medium Inertia Servo Motor

Servo Drive	ASD-B2-2023-□
Medium Inertia Servo Motor	ECMA-E∆1820⊡S
Power Cables (Without Brake)	ASD-CAPW220X
Power Cables (With Brake)	ASD-CAPW230X
Power Connectors	ASD-CAPW2000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

 $(X=3 \ indicates \ that \ the \ cable \ length \ is \ 3m; \ X=5 \ indicates \ that \ the \ cable \ length \ is \ 5m)$

3kW Servo Drive and 3kW Low Inertia Servo Motor

Servo Drive	ASD-B2-3023-□
Low Inertia Servo Motor	ECMA-C∆1330□4
Power Cables (Without Brake)	ASDBCAPW120X
Power Cables (With Brake)	ASDBCAPW130X
Power Connectors	ASD-CAPW1000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

3kW Servo Drive and 3kW Medium Inertia Servo Motor

Servo Drive	ASD-B2-3023-□
Medium Inertia Servo Motor	ECMA-F∆1830⊡S
Power Cables (Without Brake)	ASD-CAPW220X
Power Cables (With Brake)	ASD-CAPW230X
Power Connectors	ASD-CAPW2000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

3kW Servo Drive and 3.5kW Medium Inertia Servo Motor

Servo Drive	ASD-B2-3023-□
Medium Inertia Servo Motor	ECMA-F∆1835⊡S
Power Cables (Without Brake)	ASD-CAPW220X
Power Cables (With Brake)	ASD-CAPW230X
Power Connectors	ASD-CAPW2000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000

(X=3 indicates that the cable length is 3m; X=5 indicates that the cable length is 5m)

3kW Servo Drive and 3kW Medium Inertia Servo Motor

Servo Drive	ASD-B2-3023-□
Medium Inertia Servo Motor	ECMA-F∆1830⊡S
Power Cables (Without Brake)	ASD-CAPW220X
Power Cables (With Brake)	ASD-CPW230X
Power Connectors	ASD-CAPW2000
Encoder Cables	ASDBCAEN100X
Encoder Connectors	ASDBCAEN1000





Smarter. Greener. Together.

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^{*}We reserve the right to change the information in this catalogue without prior notice.